


Sommario

| | |
|-----------------------------------------------------------------------------------|----|
| MMF_P1R44F-009 : Start Up manual | 3 |
| 1. Informations | 3 |
| 1.1 Release | 3 |
| 1.2 Specifications | 3 |
| 2. Setting | 4 |
| 2.1 General view machine | 4 |
| 2.2 Belt setting | 5 |
| Belt axis resolution | 5 |
| 2.3 Bridge Setting | 6 |
| Bridge Alignment with Sensor Bar | 6 |
| Bridge resolution | 6 |
| Bridge calibration | 7 |
| Calibration | 7 |
| Dynamic calibration | 9 |
| 2.4 Sensor setup | 11 |
| Interaxes | 12 |
| Heads parameters | 13 |
| 2.4.1 Set the heads up / down advance, in relation to the movement of the bridge. | 16 |
| Orthogonal correction | 16 |
| 2.4.2 Set the heads up / down advance, in relation to the movement of the belt. | 17 |
| Horizontal Correction | 17 |
| 3. Support | 19 |
| Request for assistance | 19 |
| Repair | 19 |
| Shipping | 19 |

MMF_P1R44F-009 : Start Up manual

1. Informations

1.1 Release

|  | | | |
|-----------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------|------------|
| Document: | mmf_p1r44f-009 | | |
| Description: | Start up Manual p1r44f-009 | | |
| Editor: | Andrea Zarantonello | | |
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| Language: | English | | |
| Release document | Description | Note | Date |
| 01 | New manual | | 30/11/2022 |

1.2 Specifications

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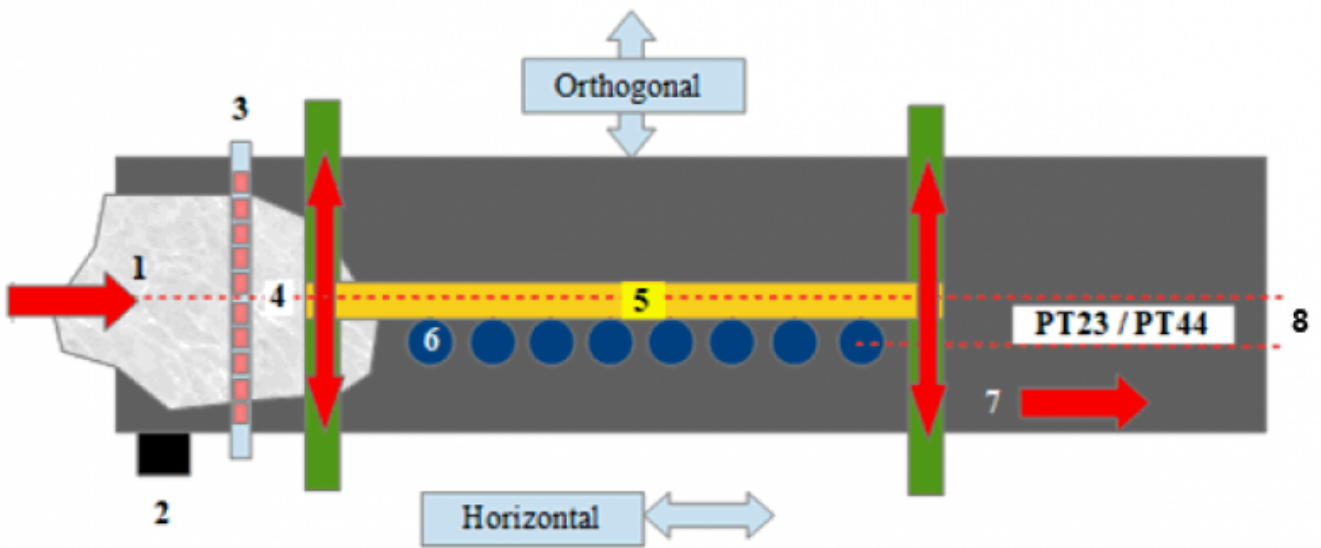
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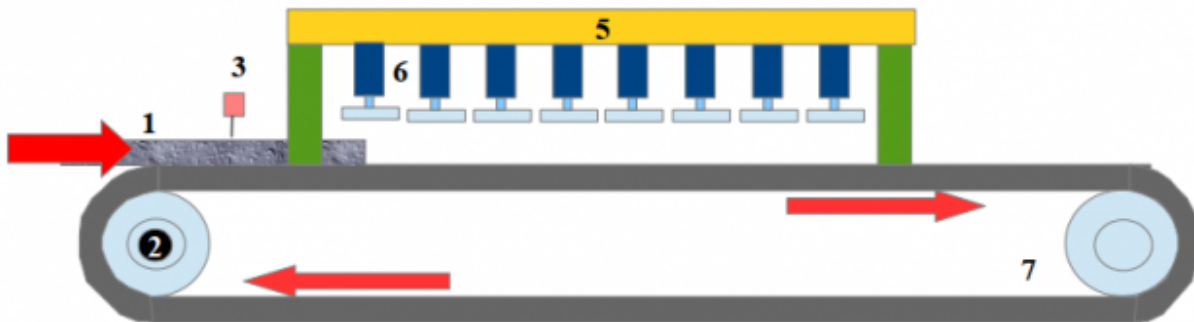
2. Setting

2.1 General view machine

Machine view from above:



Machine view from right side:




| n: | Description: |
|----|----------------------------------------------------------|
| 1 | Raw slab |
| 2 | Belt Encoder |
| 3 | Limit sensor bar |
| 4 | Center of the sensors / centre of the bridge axis travel |
| 5 | Bridge |
| 6 | Polishing heads |
| 7 | Belt direction |
| 8 | Orthogonal Offset |

2.2 Belt setting

Belt axis resolution



PROCEDURE

| | |
|---|---------------------------------------------------------------------------------------------------------------------------------|
| 1 | Make a mark on the belt and a corresponding mark on the fixed part |
| 2 | Reset the ENCODER value with the  key |
| 3 | Move the belt approximately 4000 mm |
| 4 | Read the value in the ENCODER parameter and set the PULSE parameter with the same value |
| 5 | Using a meter, measure the distance between the mark on the fixed part and the mark on the belt |
| 6 | Enter the measurement in the MEASURE field |

2.3 Bridge Setting



Bridge Alignment with Sensor Bar

The bridge, to be aligned with the sensor bar, must have the 0 sensor aligned with the first detection sensor. To have the 0 sensor and the first sensor of the bar perfectly aligned, it is recommended to use a laser indicator

Bridge resolution



Procedure

- | | |
|---|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1 | By pressing the " - " key, the instrument provides - 1 Volt |
| 2 | By pressing the " + " key the instrument provides + 1 Volt |
| 3 | Press the " - " key, bring the bridge axis towards an extreme (without touching the limit switch) |
| 4 | Make a mark on the mobile part, correspondingly make a mark on the fixed part |
| 5 |  Reset the ENCODER value with the  key. |
| 6 | With the " + " key move the axis towards the opposite extreme (without touching the limit switch) |
| 7 | Use a meter to measure the distance between the mark on the fixed part and the mark on the mobile part |
| 8 | Enter the measurement in the MEASURE |
| 9 | Copy the number of the ENCODER field to the PULSE |

Bridge calibration

Important : Need to act on the parameters of inverter / Brushless Driver / servo valves to eliminate the ramp (the ramps will be managed by the instrument)

Calibration

| | |
|---|-----------------------------------------------------------------------------------|
| 1 | Using the "BRIDGE RESOLUTION" page, bring the bridge axis to the center of travel |
| 2 | reset with the key " = 0 " |
| 3 | go to the " BRIDGE CALIBRATION" page |

| | |
|----|------------------------------------------------------------------------------------------------------------------|
| 4 | Disconnect the control leads (+/-10 Volt) Inverter/Driver/servo valves |
| 5 | Calibrate the Inverter/Driver/Servo Valves devices so that you have high sensitivity |
| 6 | Make a short circuit of the analog control inputs of the Inverter/Driver/Valve Servo devices |
| 7 | Calibrate the OffSet of the Inverter/Driver/Servo valves device so that the bridge axis stays still (don't move) |
| 8 | Connect the analog control leads to the Inverter/Driver/Valve servo |
| 9 | Press the "A" key, the instrument will automatically calculate the OFFSET voltage |
| 10 | Move the bridge axis to 1/5 of the travel |
| 11 | Enter the value 1 V in the "OUT VOLTAGE" field |
| 12 | Read the velocity |
| 13 | Multiply the velocity value by 10, then enter it in the "maximum velocity" field |

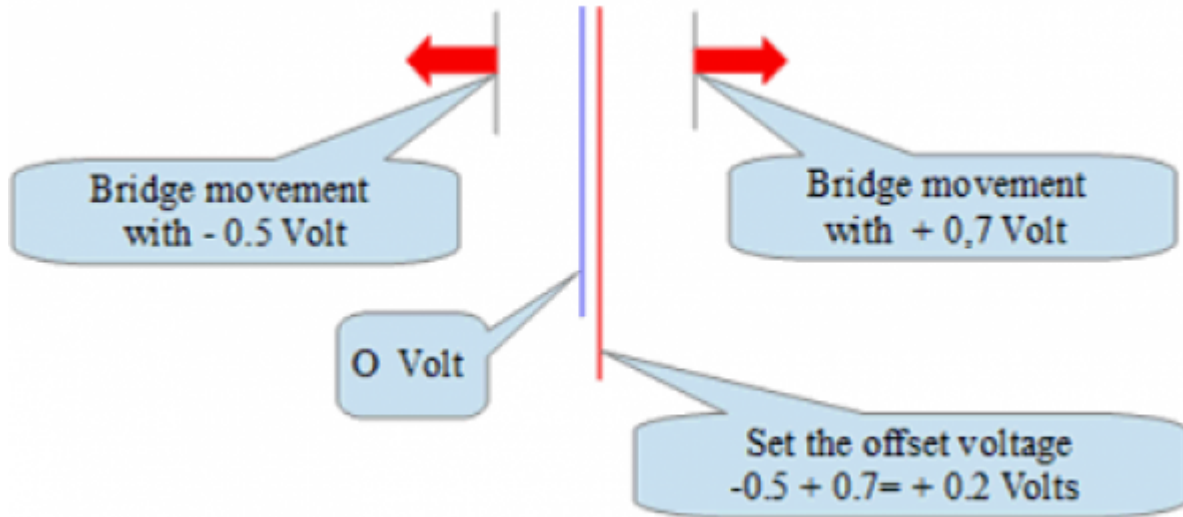
Warning: If the automatic OffSet voltage calculation procedure (point 9) fails, perform the following manual procedure:

To determine :

1. with which value of the positive voltage the bridge moves forward
2. with which value of the negative voltage the bridge moves back

then, set the offset voltage at halfway of these two values

Example :



Dynamic calibration

| | |
|----|------------------------------------------------------------------------------|
| 1 | Bring the bridge axis to 1/5 (20%) of the travel |
| 2 | Press the " = 0 " key |
| 3 | Enter a value in the "DELTA" field, a value equal to 4/5 (80%) of the travel |
| 4 | Set INTEGRAL TIME= 0 |
| 5 | Set FEEDFORWARD= 0 |
| 6 | Set PROP.GAIN = 0.02 |
| 7 | Set ACC TIME = 3 |
| 8 | Set DEC TIME = 3 |
| 9 | Set MAX FOLL ERROR = 9999 |
| 10 | Set the speed value equal to 30% of the maximum speed |
| 11 | Press Start |
| 12 | The bridge will begin to swing |

Do the following activities repeatedly, calmly, the goals are as follows:

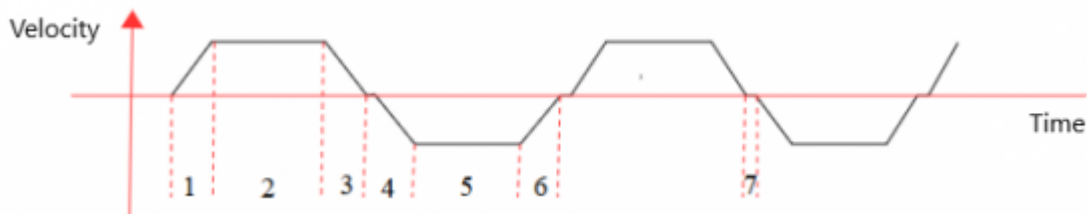
- speed as fast as possible
- acceleration ramps as short as possible
- low follow error

Method:

| | |
|---|-------------------------------------------------------------------------------|
| 1 | Increase the PROP.GAIN parameter slightly (example = 0.03 ...0.04...0.05 ...) |
| 2 | Observe if the following error is less than 30 mm |
| 3 | Then, decrease ACC TIME and DEC TIME a little bit |
| 4 | Increase the PROP.GAIN parameter slightly |
| 5 | Observe if the following error is less than 30 mm |
| 6 | Increase the speed from 30% to 40% |
| 7 | Increase the PROP.GAIN parameter slightly |

Repeat from 1 to 7 until the axis vibrates.

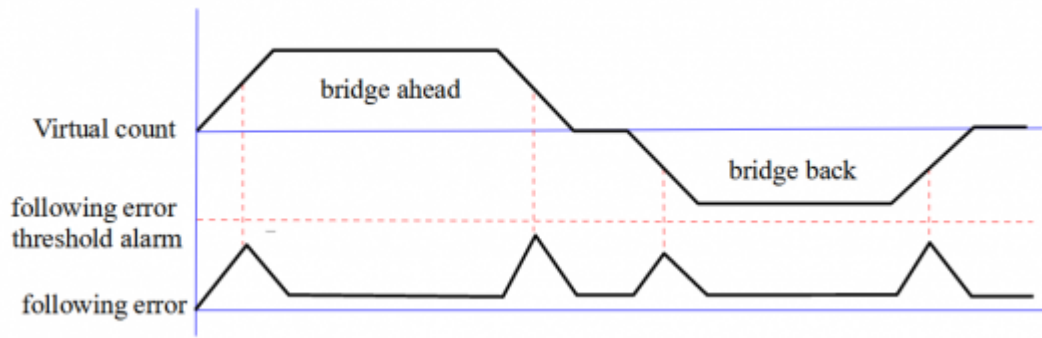
When the axis vibrates, set the PROP.GAIN to - 10 %



| | Description | Parameter |
|---|---------------------------------|-----------|
| 1 | Positive Direction Acceleration | PB 08 |
| 2 | Constant speed | |
| 3 | Deceleration | PB 09 |
| 4 | Negative Direction Acceleration | PB 08 |
| 5 | Constant speed | |
| 6 | Deceleration | PB 09 |
| 7 | Pause | PB 10 |

Note: accelerations/decelerations with "S" ramps (parameter "PG 34") decreases the number of right-left cycles, but it helps to make the movement of the lift more harmonious



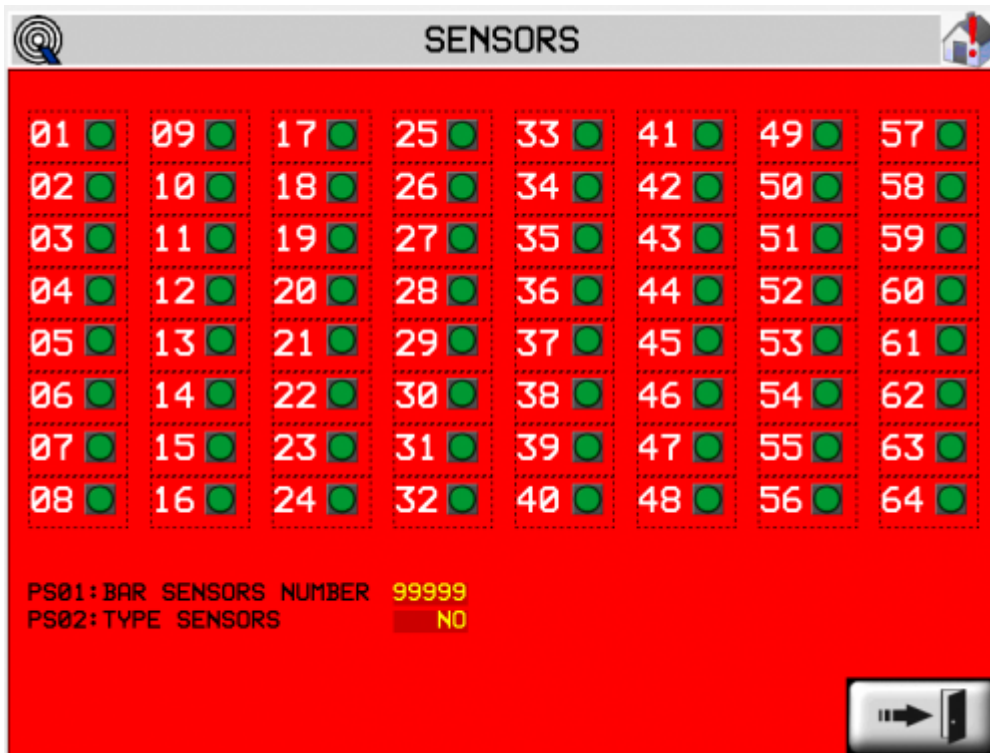
Setting following error:

- With the bridge moving, lower the following error value from 9999 to 100.
- Then, progressively with small variations, decrease the value from 100 towards 0000.
- Found the value that will trigger the alarm, add a 15%

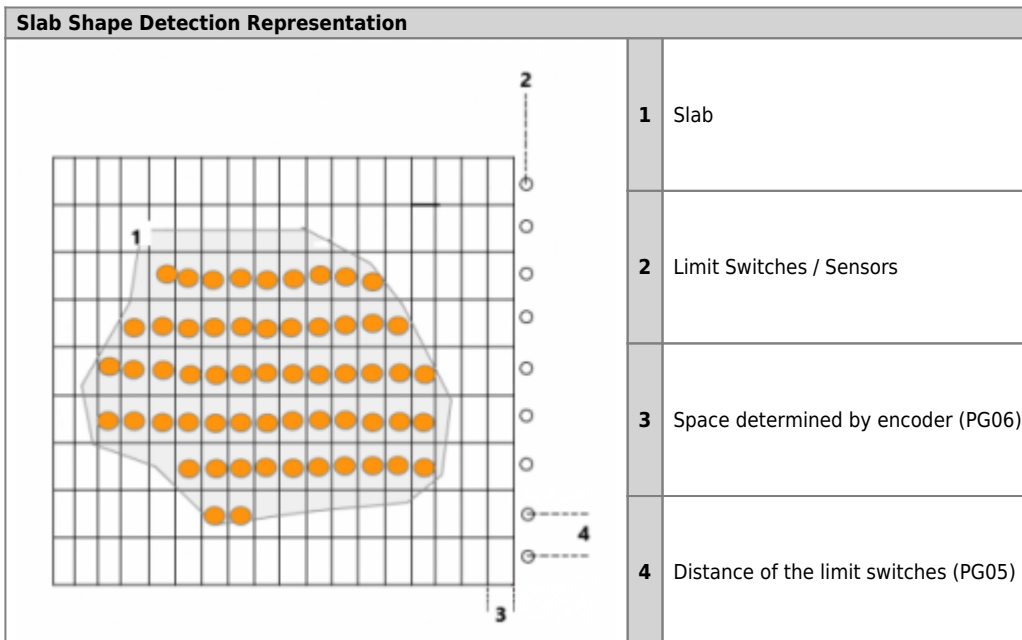
Warning: The follow error must be less than 30.

2.4 Sensor setup

- Align the sensor bar with the bridge: [Alignment](#)
- position the sensors, so that **the center of the bridge travel corresponds to the center of the sensors** (see [main image](#))
- set the number (parameter PS01) and the type (parameter PS02) of sensors in the SENSORS page



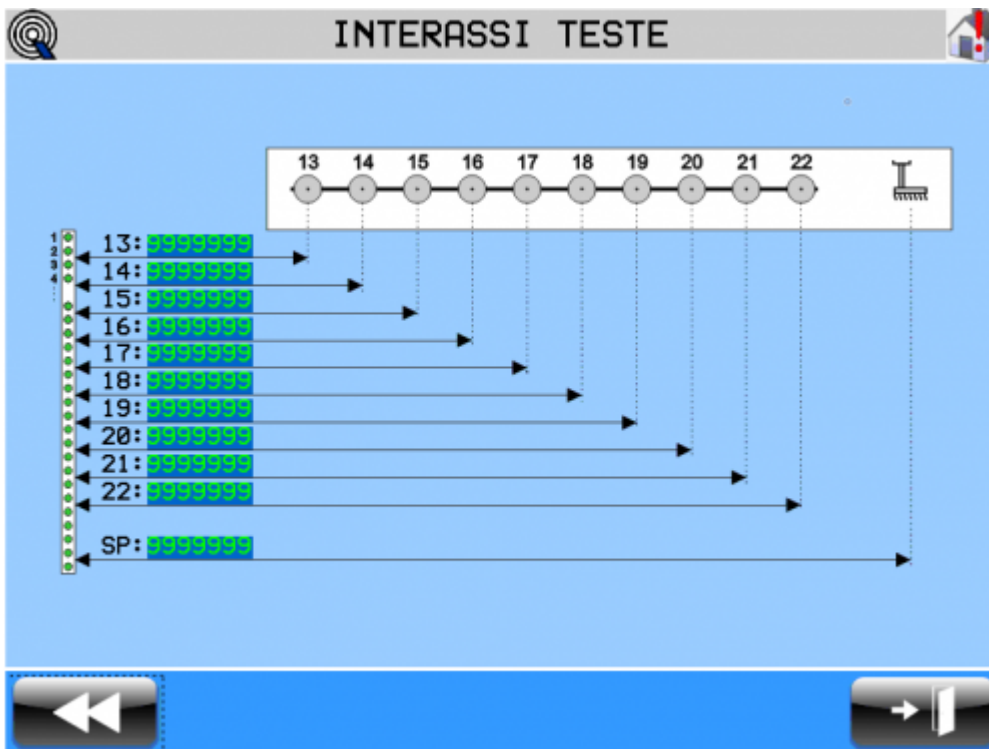
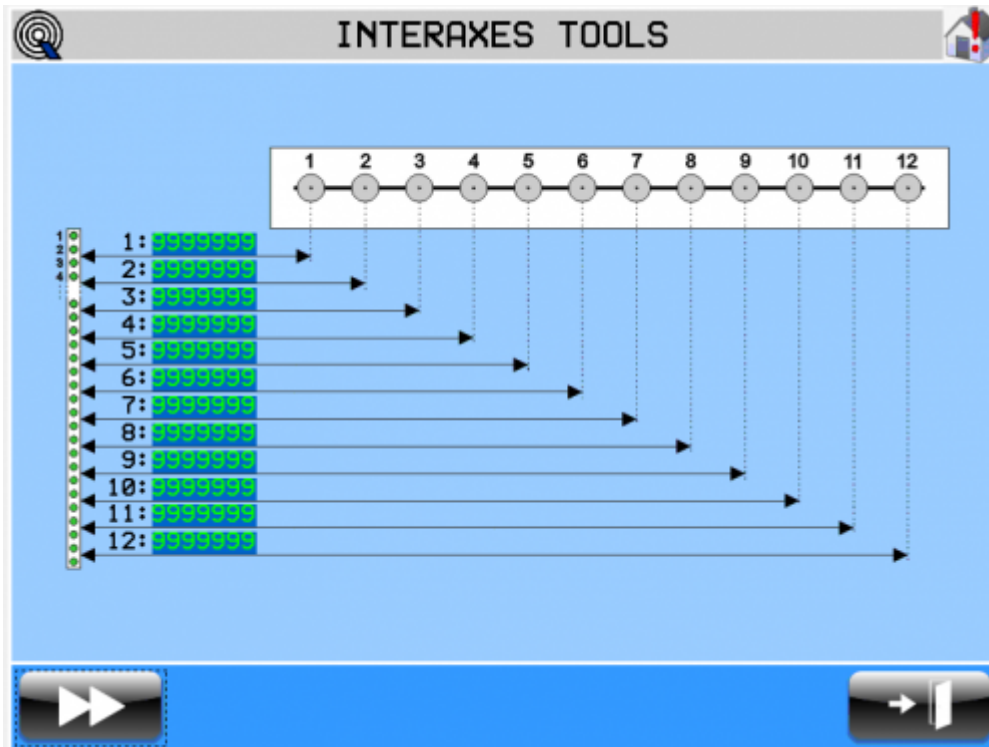
- set the parameter PG05:Orthogonal Step (distance of the sensors) and the parameter PG06:Horizontal Step (space determined by the encoder) in the generic SETUP page



- check the functionality of the slab detection sensors on the DIAGNOSTICS 2 page. If the limit switches detect the presence of the slab, the LEDs light up.

Interaxes

Set in INTERAXES TOOLS page, the distance (mm) of every polishing head (and brush) compared to the acquisition sensor bar (limit switches)



Heads parameters

| TOOLS | | | |
|------------------|------------------|-----------------------------|----------------------|
| | DIAMETER | ORTHOGONAL OFFSET | TIME TO PARTIAL LIFT |
| 1 | PT01: 9999999 mm | PT23: 9999999 mm | PT45: 9999999 s |
| 2 | PT02: 9999999 mm | PT24: 9999999 mm | PT46: 9999999 s |
| 3 | PT03: 9999999 mm | PT25: 9999999 mm | PT47: 9999999 s |
| 4 | PT04: 9999999 mm | PT26: 9999999 mm | PT48: 9999999 s |
| 5 | PT05: 9999999 mm | PT27: 9999999 mm | PT49: 9999999 s |
| 6 | PT06: 9999999 mm | PT28: 9999999 mm | PT50: 9999999 s |
| 7 | PT07: 9999999 mm | PT29: 9999999 mm | PT51: 9999999 s |
| 8 | PT08: 9999999 mm | PT30: 9999999 mm | PT52: 9999999 s |
| 9 | PT09: 9999999 mm | PT31: 9999999 mm | PT53: 9999999 s |
| 10 | PT10: 9999999 mm | PT32: 9999999 mm | PT54: 9999999 s |
| 11 | PT11: 9999999 mm | PT33: 9999999 mm | PT55: 9999999 s |
| 12 | PT12: 9999999 mm | PT34: 9999999 mm | PT56: 9999999 s |
| 13 | PT13: 9999999 mm | PT35: 9999999 mm | PT57: 9999999 s |
| 14 | PT14: 9999999 mm | PT36: 9999999 mm | PT58: 9999999 s |
| 15 | PT15: 9999999 mm | PT37: 9999999 mm | PT59: 9999999 s |
| 16 | PT16: 9999999 mm | PT38: 9999999 mm | PT60: 9999999 s |
| 17 | PT17: 9999999 mm | PT39: 9999999 mm | PT61: 9999999 s |
| 18 | PT18: 9999999 mm | PT40: 9999999 mm | PT62: 9999999 s |
| 19 | PT19: 9999999 mm | PT41: 9999999 mm | PT63: 9999999 s |
| 20 | PT20: 9999999 mm | PT42: 9999999 mm | PT64: 9999999 s |
| 21 | PT21: 9999999 mm | PT43: 9999999 mm | PT65: 9999999 s |
| 22 | PT22: 9999999 mm | PT44: 9999999 mm | PT66: 9999999 s |
| PT67: BRAKE MODE | | Out Off with break Activate | |
| PT68: LIFT DELAY | | 9999999 s | |

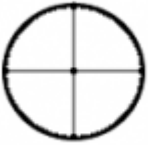


- Set diameter of the heads:

PT 01 ÷ 22



The diameter of the head passes through the center of the tools

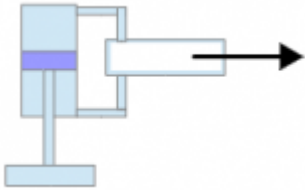
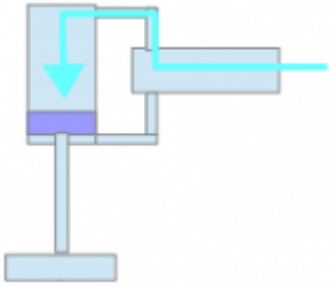
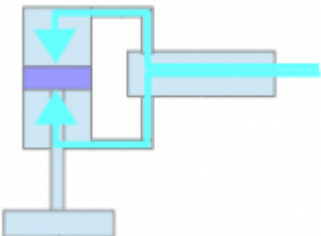
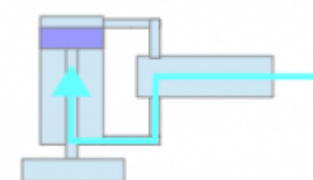
The diameter of the heads is important because the descent and ascent of the heads follow a specific criteria:

| | | |
|---|-----------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------|
| 1 |  | The head's area is divided in 4 parts |
| 2 |  | The head goes down (descent) only if at least 3 of 4 parts see the slab underneath |
| 3 |  | The head goes up (ascent) only if the parts seeing the slab underneath pass from 3 to 2 |

- **Set orthogonal offset (distance from the working head and the middle line of the bridge) PT 23 ÷ 44**

Attention:the minimum value of orthogonal offset is 1

- Set “Time to partial lift”: PT 45 ÷ 66
- Set “Lift delay”: PT 68

| “Closed center” Solenoid valves up and down heads | | Parameters: |
|-------------------------------------------------------------------------------------|---------------|-------------|
|  | Valve | |
|  | Cylinder down | |
|  | Closed center | PT 45 ÷ 66 |
|  | Cylinder up | PT 68 |

In order to descend quickly, the travel of the cylinder is decreased:

By setting the partial ascent time of the head (parameters 45 ÷ 66) the ascent output is de-energized after that time.

Mechanically, when the ascent and descent are de-energized, the upper chamber is in communication with the lower chamber of the cylinder, locking it in that position (closed centers).

The total ascent will be done only when the head has no longer to work.


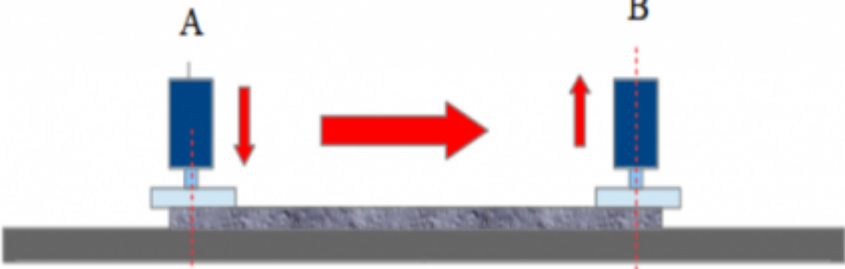
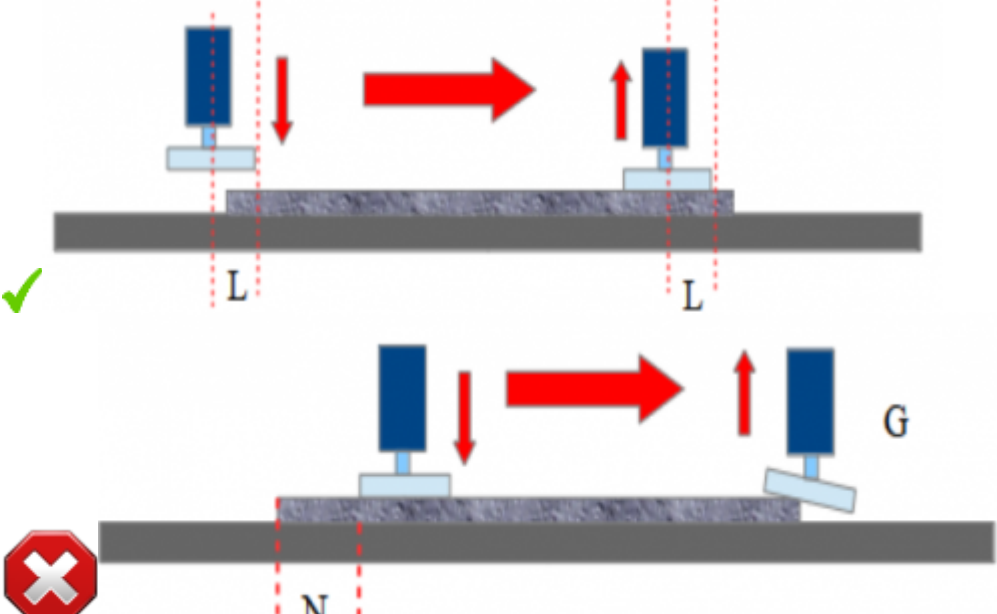
2.4.1 Set the heads up / down advance, in relation to the movement of the bridge.

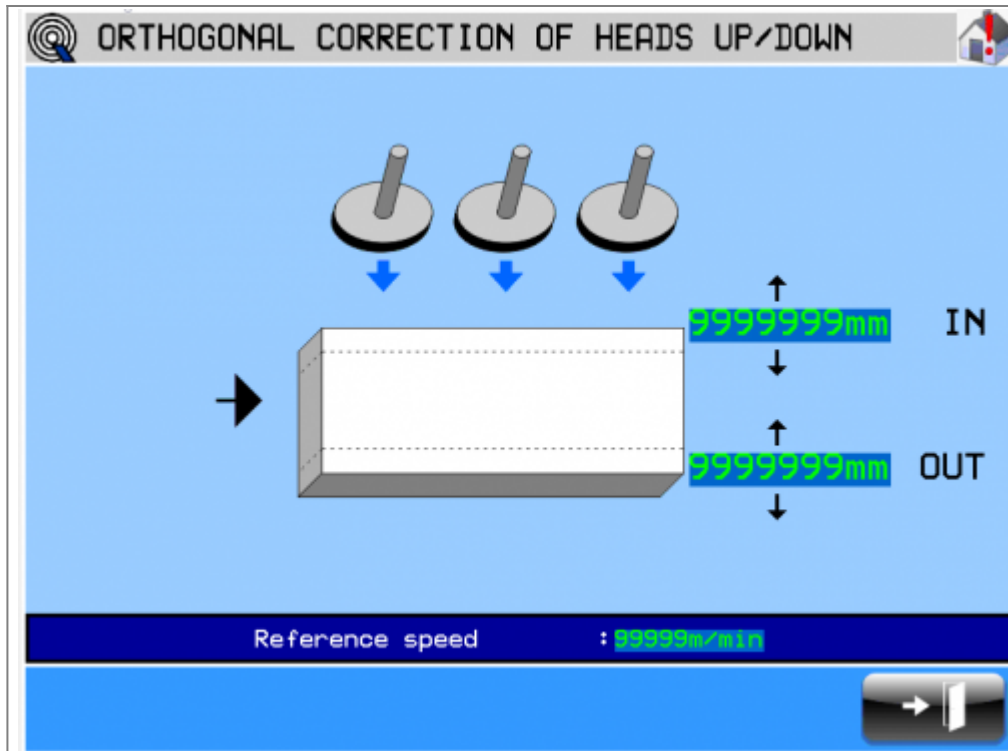
Orthogonal correction

It is very important that the bridge is exactly in the position where it should be, otherwise the descent and ascent commands of the heads cannot be performed correctly.

So it's very important that the following error (difference between the virtual and real position) is the minimum possible

- Remove the abrasives and make sure that the heads, going down, cannot damage the belt
- Set the conveyor belt at a low speed
- Set the bridge at maximum speed

| | |
|--------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  | <p>The blue arrow indicates the slab entering in the polishing machine. P is the observation point, observe the behavior of the first head</p> |
|  | <p>If the bridge goes slow the head goes down to point A and goes up to point B</p> |
|  | <p>If the bridge goes fast the ascent and descent commands must be anticipated (point L) so that the head descends shortly after the left edge and rises just before the right edge of the slab</p> <p>otherwise the first part of the slab would not be polished (point N) and the polishing tool would tilt, damaging the edges of the slab (point G)</p> <p>Important : set the advance of the descent very well</p> |

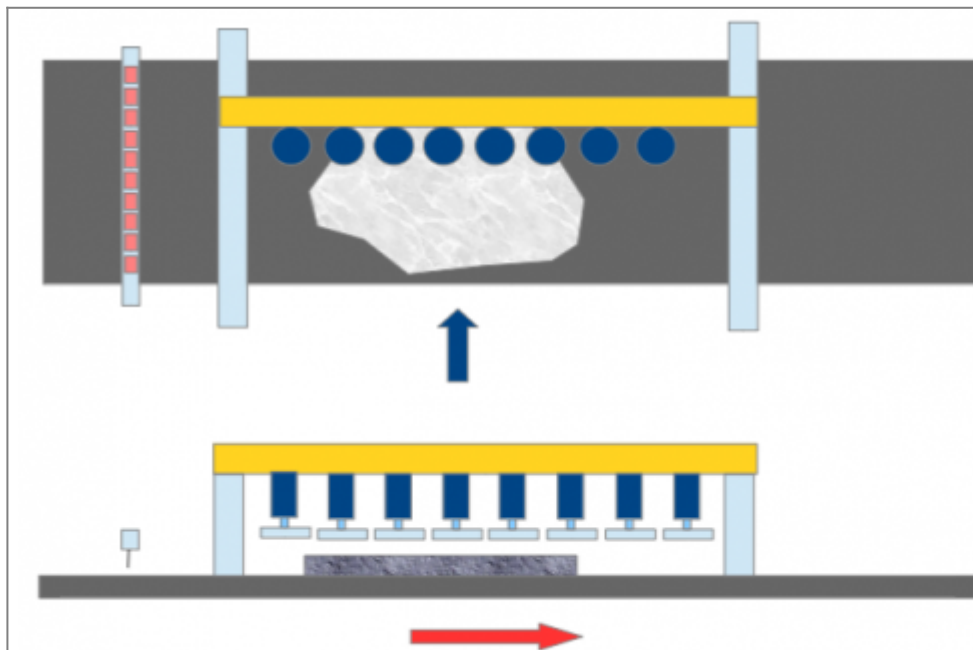


Page where you need to act to anticipate / postpone the heads. In the parameter **"reference speed"** you need to insert the speed of the bridge. If you don't put a value in "reference speed", the correction parameters are not adapted to each speed change of the bridge.

2.4.2 Set the heads up / down advance, in relation to the movement of the belt.

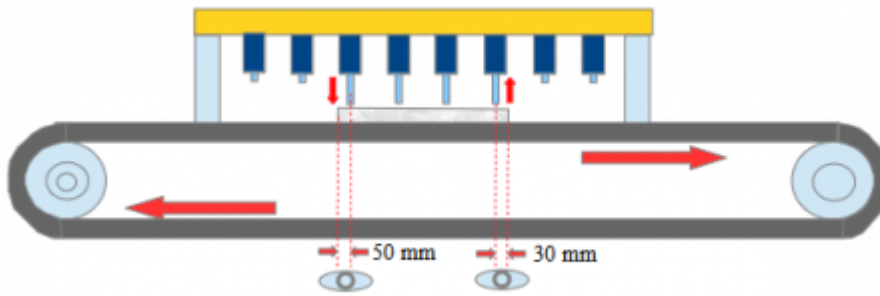
Horizontal Correction

- Remove the abrasives and make sure that the heads, going down, cannot damage the belt
- Set the tape to maximum speed

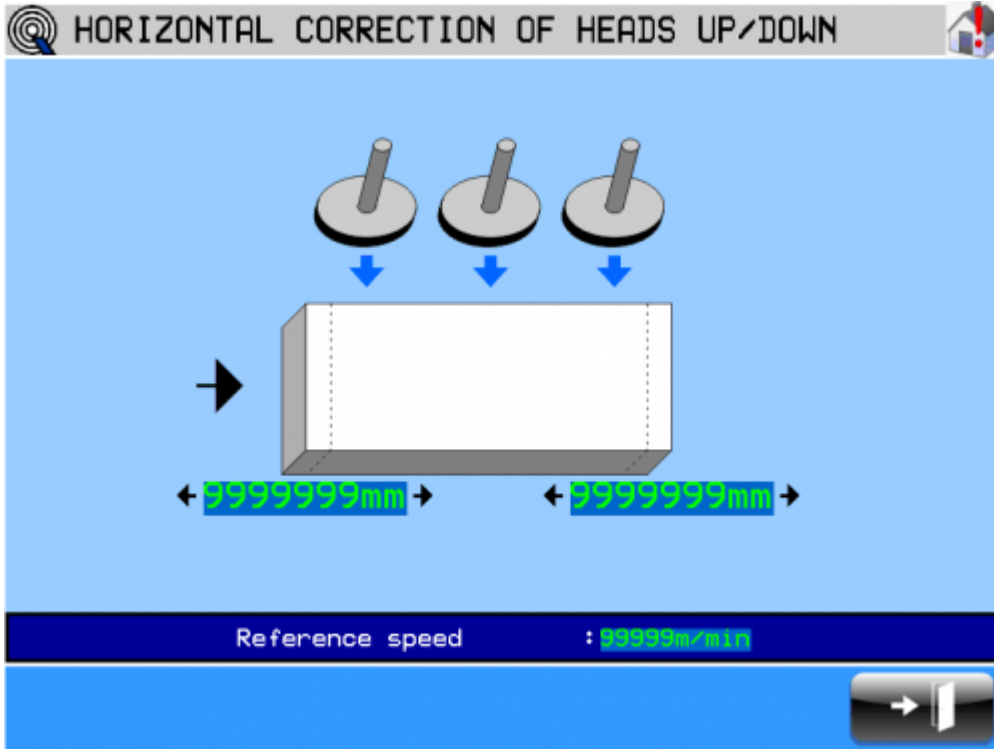


The blue arrow indicates the observation point. The conveyor belt goes slowly, typically 3000 mm per minute so the advance space for the descent and ascent of the heads is "minimum"

The red arrow indicates the direction of travel of the conveyor belt.



As seen in the previous method, calibrate the up and down advance so that the heads work on the entire surface of the slab, taking care not to go beyond the edges.





Page where you need to advance/postpone the heads
In the parameter **"reference speed"** you need to insert the speed of the bridge. If you don't put a value in "reference speed", the correction parameters are not adapted to each speed change of the bridge.

- Set a low belt speed, then check if the head ascent and descent has remained correct

3. Support

Request for assistance

In order to be able to provide you a quick service, at the minimum cost, we need your help.




| | |
|-----------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  |  |
| <p>Follow all the instructions provided in the manual MIMAT</p> | <p>If the problem persists, fill in the "Assistance request form" on the page Contacts of the site www.qem.it. Our technicians will obtain essential elements for understanding your problem.</p> |

Repair

In order to provide you with an efficient service, please read and follow the instructions here [reported](#)

Shipping

It is recommended to pack the instrument with materials that can absorb any falls.

| | | |
|-------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  |  |  |
| <p>Use the original packaging: it must protect the instrument during transport.</p> | <p>Attach: 1. A description of the anomaly; 2. Part of the wiring diagram where the instrument is inserted 3. Programming the instrument (set up, work quotas, parameters ...).</p> | <p>A thorough description of the problem will allow us to quickly identify and resolve your problem. Careful packaging will avoid further inconveniences.</p> |

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