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MDI_P1P20F - 022 : Installation manual

1. Informations

1.1 Release

This document is valid in its entirety except for errors or omissions.

			
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Release document	Description	Note	Date
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1.1.1 Specifications/Copyright

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2. Description

The **P1P20F - 022** software, controls the automation of **sanders/smoothing** machines.

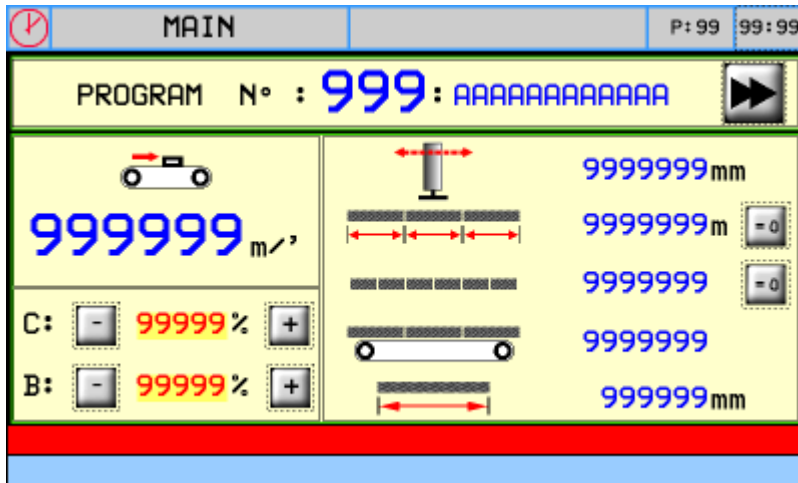
Main features

- control of **20 heads**
- control the **sequential start-up of motors** (to limit the excessive current demand)
- also control of the **bridge move**
- for each head you can set **advances/delays working** to the **start/end** of the piece
- the ascent/descent controls of the sanding heads, calculated **automatically as the speed** of the conveyor belt changes
- counts the **meters worked** and is able to work up to **30 pieces** at the same time

Other features

- HMI with touchscreen
- Function keys
- Work programs
- Alarm messages
- Warning messages
- Reset defective pieces
- Reset of all piece in process
- Offset correction of part presence limit
- How heads are processed
 1. Sanding
 2. Milling
 3. Grinding
 4. Brushing
 5. Water jet

3. Main Page



3.1 Command bars and information

The bars at the top and bottom of each page provide the following information:

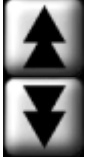


A	Machine states
B	Page name
C	Additional page description
D	Page number
E	Watch
F	Alarm on (red background)
G	Warning (blue background)
	Current speed of conveyor belt
N:	Setting conveyor belt speed
P:	Setting bridge speed
	Position of the Bridge
	Machined linear meters
	Number of total work pieces
	Number of pieces currently being processed in the machine
	Last piece length in process

3.2 Machine states

Simbol	Description
	Manual
	Emergency
	Automatic
	Works mode
	Calibration
	Not used

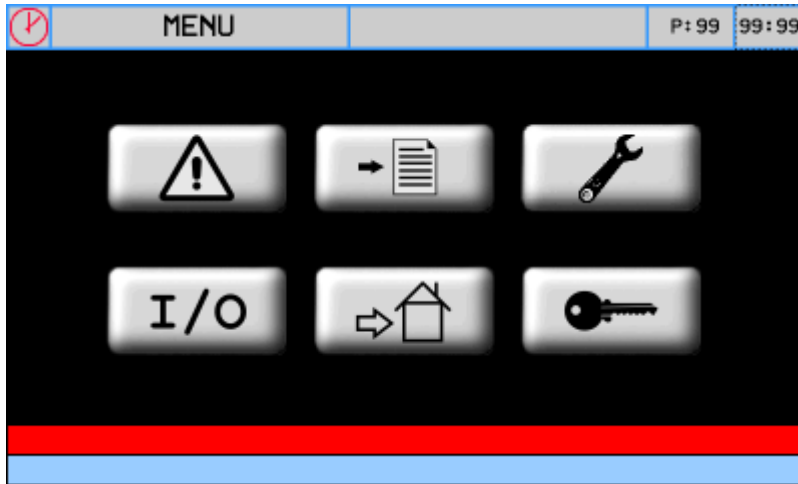
3.3 Common keys

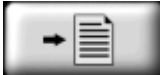
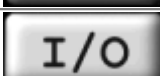
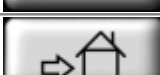
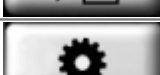
Simbol	Description
	Scroll through programs
	Save and exit: setup values that you set are saved to internal memory and executed
	Open program
	Page forward
	Page backward
	Exit without saving: the setup values entered are not saved and the values in the internal memory are reloaded
	MENU page
	SETUP page (protected with password)
	WORK PROGRAMS
	RESET TOTAL PIECES
	RESET PARTIAL PIECES
	ALARMS
	Page exit

• 4. Main Menu



From **MAIN PAGE** press the key



	Alarms
	Access to programs
	Functions menu
	Diagnostic
	Homing bridge
	Access to setup

• 4.1 Password

Installer Password **462**

5. First start-up



For proper start-up of the machine, it's recommended to follow the order of the activities described below

J1-P20F Controller's Preliminary Calibration

1. HMI calibration (**Touch calibration** screen and setting of the **language**)

Machine Settings

1. Check the correctness of the **GP** and **MP** parameters (**Generic parameters** and **Machine Parameters**)
2. Check the **machine wiring** with **Diagnostics** pages
3. Check the **direction of the Conveyor and tilting Bridge** with the forward/backward controls from the manual page

Calibrations

1. Check the **Counter Direction** and calibrate the **Conveyor Belt Resolution**
2. Calibrate the maximum speed of the conveyor belt
3. Calibrate the **offset of the "piece presence" limit switch**
4. **Heads calibrating**
 1. Tool diameter
 2. Introduce **distance of heads from the end of the limit switch of presence piece**
 3. **Calibration of dynamic corrections ascent/descent heads** depending on the speed of the conveyor belt

5.1 Accessing the Setup

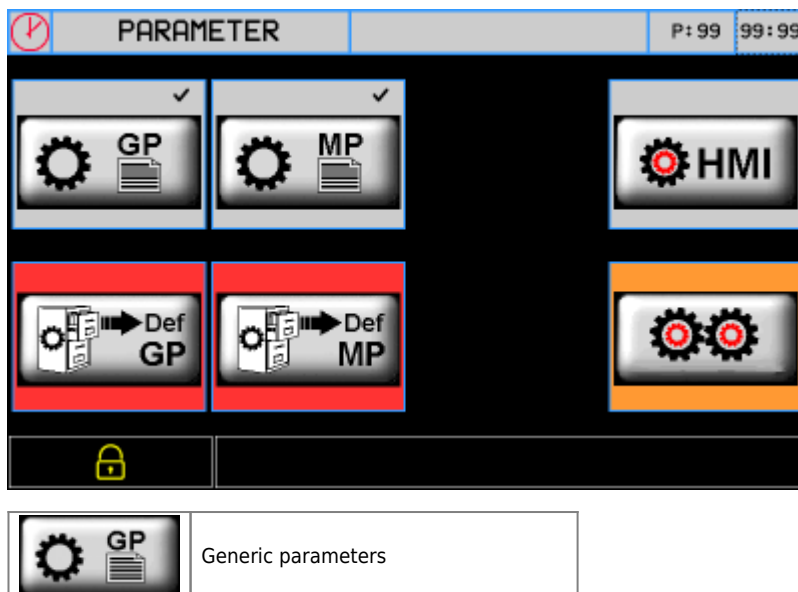
You can access the setup in two modes:

1. from the **MENU** page press  key

2. from the **MAIN PAGE** press  function key



Access granted only if there aren't parts in the machine



	Machine parameters
	Load default generic parameters
	Load default machine parameters
	HMI Calibration
	Conveyor, bridge and heads calibration



To disable the password until the next restart press



, the icon must become



To return to the **MENU** page, press the

key

5.2 J1P20F Preliminary Settings

5.2.1 HMI Calibration



To access from the **SETUP** page press the

key

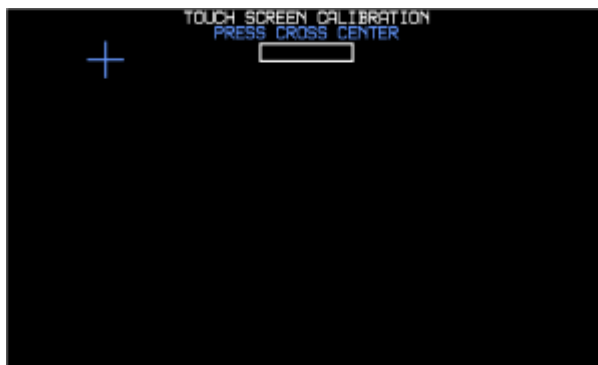


Parameter name	Default	Range	Description
LOGO	ON	OFF ÷ ON	OFF : logo not showed ON : logo showed
LANGUAGE	en_GB	-	en_GB : english it_IT : italian
BUZZER	ON	OFF ÷ ON	OFF : disable ON : enable
DATA	-	-	Insert data
TIME	-	-	Insert time
DAYLING SAVING TIME	OFF	OFF ÷ ON	OFF : disable ON : enable



To calibrate the touch screen, press

key



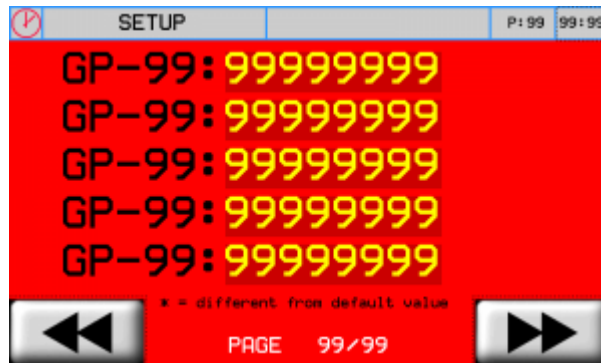
Follow the instruction.

1. 5.3 Machine settings

5.3.1 Generic parameters



To access, from the **Generic Parameters** page, press the  key



- **GP-XX** = Generic Parameters, **XX** = number
- **P.ter** = Parameters
- **U.M.** = Unit Measure
- **Def.** = Default

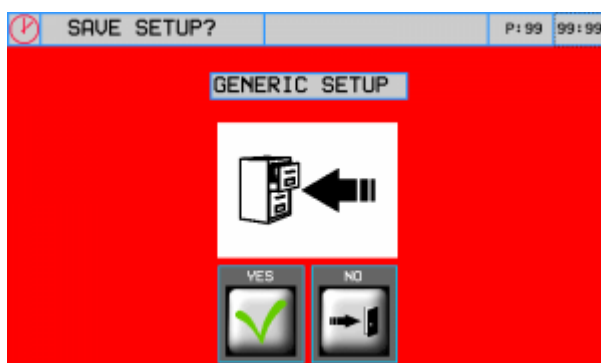
P.ter	U.M.	Def.	Range	Description
GP-01	-	4000	P (Pulse)	Encoder pulses x 4 corresponding to the space set in the Measure .
GP-02	-	400.0	M (Measure)	Space corresponding to the encoder pulses in the Pulse parameter. Note: - the P/M ratio must be between 0.000935 and 4.000000.
GP-03	-	1	0 ÷ 3	Decimal point position on the measurement of the conveyor belt view. 0 =xxxx, 1 =xxx.x, 2 =xx.xx, 3 =x.xxx
GP-04	-	-	-	n.u.
GP-05	-	1	0 ÷ 1	Position of heads with conveyor belt speeds below minimum (GP-06) 0 = remain in a low position 1 = go up
GP-06	-	0.1	0 ÷ 999999	Minimum speed of the conveyor.
GP-07	-	0.5	0 ÷ 999999	Delta speed beyond which the filter intervenes (GP-08).
GP-08	msec	50	0 ÷ 9999	Filter value of the tape speed.
GP-09	-	0	0 ÷ 5	Frequenzimeter sampling time (used to determine the speed of the conveyor belt) 0 = 240 ms, 1 = 480 ms, 2 = 24 ms, 3 = 120 ms, 4 = 960 ms, 5 = 1920 ms
GP-10	-	0	0 ÷ 1	0 = Store parts when turned off 1 = Does not store parts when switched off
GP-11	-	0	0 ÷ 1	Piece acquisition (In9) below the minimum speed . 0 = Enable 1 = Disable
GP-12	mm	10.0	0 ÷ 9999	Space under which two nearby pieces are continuously machined Note: The counting of pieces always counts 2 pieces.
GP-13	-	-	-	n.u.
GP-14	msec	1000	0 ÷ 9999	Time T1 between starting a motor and the next
GP-15	msec	1000	0 ÷ 9999	Time T2 between the start of the last motor and the activation of the end start motor output O18
GP-16	-	0	0 ÷ 1	Position abrasive change. 0 = backward limit-switch 1 = forward limit-switch
GP-17	-	0	0 ÷ 1	Carter Contact Activation Status. 0 = NC (Normally Closed) 1 = NO (Normally Open)

P.ter	U.M.	Def.	Range	Description
GP-18	-	4000	P (Pulse) Encoder Bridge	Bridge encoder pulses x 4 corresponding to the space set in the Measure .
GP-19	-	400.0	M (Measure) Ponte	Bride Space corresponding to the encoder pulses in the Pulse parameter. Note: - the P/M ratio must be between 0.000935 and 4.000000.
GP-20	-	1	0 ÷ 3	Decimal point position on the speed Bridge view. 0 =xxxx, 1 =xxx.x, 2 =xx.xx, 3 =x.xxx
GP-21	-	1	0 ÷ 3	Decimal point position on the measure Bridge view. 0 =xxxx, 1 =xxx.x, 2 =xx.xx, 3 =x.xxx
GP-22	-	2000	-99999 ÷ 999999	Maximum measure of the Bridge.
GP-23	-	0	-99999 ÷ 999999	Minimum measure of the Bridge.
GP-24	-	100	-99999 ÷ 999999	Slow-down measure of the Bridge.
GP-25	-	0	-99999 ÷ 999999	Homing measure of the Bridge.
GP-26	-	1.0	-9999 ÷ 99999	Homing Search Speed of the Bridge.
GP-27	-	0	0 ÷ 1	Homing Search Direction of the Bridge. 0 = Forward; 1 = Backward.
GP-28	sec	0.5	0 ÷ 60.0	T3 . Time passage operation heads descent / motor start. This is the waiting time from activating I2 input, for the instrument function mode from "Head activation" to "Motor Start".
GP-29	sec	0.5	0 ÷ 60.0	T4 . Transition time from motor start/head descent operation. This is the waiting time from activating I2 input, for the instrument function mode from "Motor Start" to "Head activation".
GP-30	-	0	0 ÷ 3	Unit of measure "Time to activate/deactivate Mix Output". 0 = The ta and td deactivation time are expressed in seconds. 1 = The activation time ta is expressed in seconds, the deactivation time td is expressed in minutes. 2 = The activation time ta is expressed in minutes, the deactivation time td is expressed in seconds. 3 = The ta activation time and td deactivation time are expressed in minutes.
GP-31	-	0.5	0 ÷ 999.0	Ta . Activation time Mix output. This is the time (in minutes or seconds) to activate the U19 output (mix out) to execute the mix cycle.
GP-32	-	0.5	0 ÷ 999.0	Td . Deactivation time Mix output. This is the time (in minutes or seconds) to deactivate the U19 output (mix out) to execute the mix cycle.
GP-33	-	0	-99999 ÷ 999999	Increase/Decrease minimum and maximum measure of the Bridge. It is the value that is added or subtracted from the maximum and /or minimum measure of the Bridge by pressing the relative keys on the main page of the bridge view.
GP-34	-	3	0 ÷ 99	Number of check for piece presence input. The instrument checks the status of the input every 3 milliseconds. this parameter indicates how many checks and how many milliseconds the input must maintain logical state so that the instrument acquires the variation.



For exit from the **Generic Parameters** page, press the  key

On the display is showed:



Press **"YES"**, if you want to store the introduced parameters.
Press **"NO"**, if you want exit, without saving the introduced parameters.

1. 5.3.2 Machine parameters



To access, from the **Machine Parameters** page, press the  key



- **MP-XX** = **M**achine **P**arameters, **XX** = number
- **P.ter** = **P**arameters
- **U.M.** = **U**nit **M**easure
- **Def.** = **D**efault

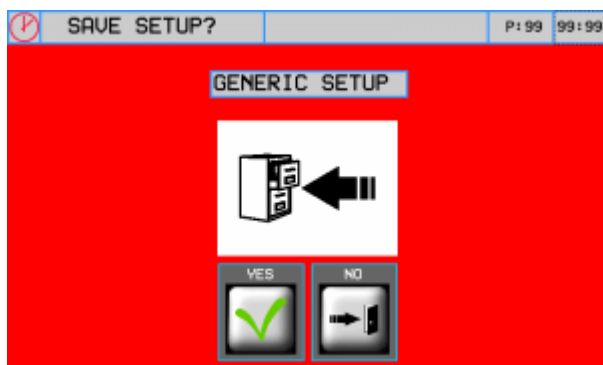
N.ter	U.M.	Def.	Range	Description
MP-01	-	1	1 ÷ 19	Heads number.
MP-02	mm	0	0 ÷ 999999	Machine length. Note: space between the piece presence sensor and the end of the machine.
MP-03	-	0	0 ÷ 2	Command/Control of the conveyor belt 0 - External Command/Control - Reading the speed. 1 - Command - reading the speed - Analog output. 2: - Command and Control with feedback from encoder - Reading the speed - Analog output - Start/Stop of the instrument
MP-04	-	0	0 ÷ 1	Bridge command 0 = External control . 1 = Bridge control with minimum, maximum limit-switch and slow-down. 2 = Bridge control with encoder minimum, maximum limit-switch and slow-down.
MP-05	-	0	0 ÷ 1	Motor Startup Sequence 0 = disable. 1 = enable to J1-P20. N.B. Motor start outputs are in common with head descent outputs. 2 = enabled on RMC module. 3 = enabled on RMC module. N.B. It is activated automatically at the input of the piece in the machine.
MP-06	-	-	-	-
MP-07	-	-	-	-
MP-08	m/'	5.0	0 ÷ 5.0	Maximum speed (AO1 = 10 Volt) of the conveyor belt (MP-03 > 0) (see " Maximum speed settings ").
MP-09	m/'	3.0	0 ÷ 5.0	Speed in automatic of the conveyor belt (MP-03 > 0)
MP-10	m/'	1.0	0 ÷ 5.0	Jog speed of the conveyor belt (MP-03 > 0).
MP-11	-	0	0 ÷ 1	Starting condition of the bridge in automatic mode (MP-04 = 1). 0 = Start with tape 1 = Start when a piece enter
MP-12	s	1.000	0 ÷ 999.0	Delay time between the conveyor belt start and bridge start (MP-05 = 1).
MP-13	%	5.0	0 ÷ 100.0	% maximum speed of the bridge in automatic mode.
MP-14	%	5.0	0 ÷ 100.0	Slow speed of the bridge in automatic mode (MP-04 = 1)
MP-15	%	50.0	0 ÷ 100.0	Jog Speed of the bridge (MP-04 = 1).

N.ter	U.M.	Def.	Range	Description
MP-16	s	2.000	0 ÷ 999.0	Bridge stop time on the maximum and minimum limit-switches (<i>MP-04</i> = 1).
MP-17	-	0	0 ÷ 1	Direction of the pieces input. 0 = right 1 = left



For exit from the **Machine Parameters** press the key

On the display is showed:

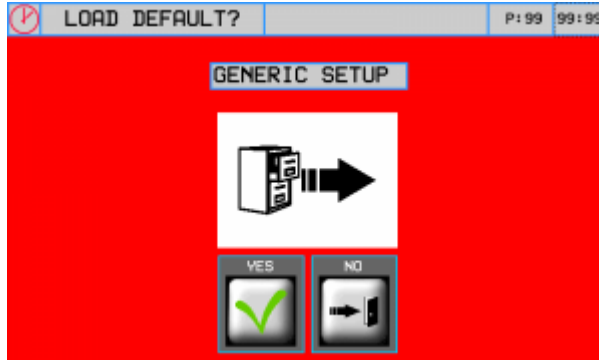


Press **"YES"**, if you want to store the introduced parameters.
Press **"NO"**, if you want exit, without saving the introduced parameters.

1. 5.3.3 Default parameters

To access to the “load default parameters” page, from the **SETUP** page:

- press the  key for load the **default generic parameters**, or
- press the  key for load the **default machine parameters**.



Press **“YES”**, if you want “load” the default generic parameters.
Press **“NO”**, if you want exit, without saving “load” the default generic parameters.

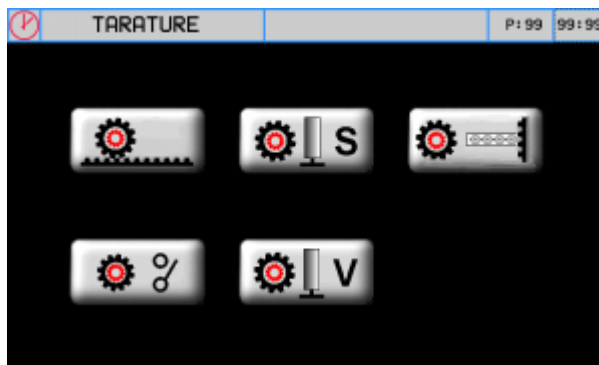
5.4 Calibrations



To access at the Calibration page, from the **SETUP** page press the key



Access is only allowed if input I5 = OFF



	Conveyor calibration
	Offset calibration of the piece presence sensor
	Set Heads parameters
	Calibration of dynamic corrections of ascent/descent heads
	Bridge calibration



To return to the **setup** page press the key

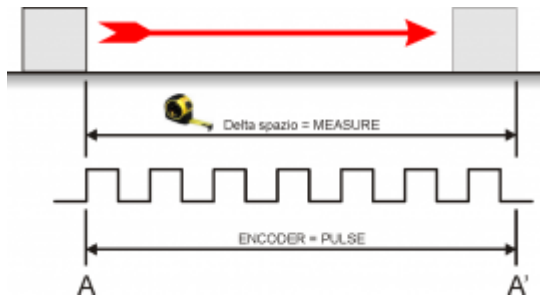
5.4.1 Conveyor calibration

To access on the conveyor calibration, press the  key

The following page appears



Procedure



- Set **1 Volt**, on the **ANALOG OUTPUT** parameter
- Presse the  key (Analog output +1 Volt), check that the value of the ENCODER parameter increases (if it decreases, the two phases of the encoder in the CN9 connector must be reversed).
- A - A' = Longest possible space
- Mark the starting position (A)
- Reset the **ENCODER** value: 
- Execute the movement from A to A'
- Write on the **PULSE** parameter, the value showed in the **ENCODER** parameter
- Measure the **delta space** A - A'
- Write the **delta space** value A - A' on the **MEASURE** parameter
- verify the value that appears in the **VEL** parameter, when you press the  key
- The **maximum speed** value of the conveyor will be **10 times** larger than the **VEL** showed. this value should be written to the **MP-08** parameter

Important:

- The **PULSE** value must always be greater than the value of **MEASURE** (the optimal value is "MEASURE x 10 = PULSE")
- Introduce the **MEASURE** value into the **unit of measure** that you choosen. Example: if you choose 1/10mm unit of measure and the **delta space** measure is 133.5mm, introduce the value 1335 into the **MEASURE** parameter
- The **Pulse** and **Measure** parameters inserted here, will be automatically transcribed into the **GP-01** and **GP-02** parameters

For exit from the **Conveyor calibration** page press the  key

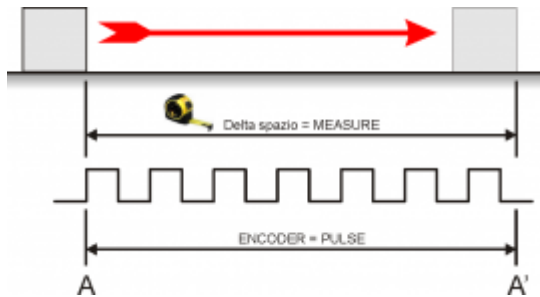
1. 5.4.2 Bridge calibration

To access on the calibration of the Bridge, press the  key

The following page appears



Procedura



- Set **1 Volt**, on the **ANALOG OUTPUT** parameter
- Presse the  key (Out analogica +1 Volt), check that the value of the **ENCORDER** parameter increases (if it decreases, the two phases of the encoder in the **CN10** connector must be reversed).
- A - A' = Longest possible space
- Mark the starting position (A)
- Reset the **ENCORDER** value: 
- Execute the movement from A to A'
- Write on the **PULSE** parameter, the value showed in the **ENCORDER** parameter
- Measure the **delta space** A - A'
- Write the **delta space** value A - A' on the **MEASURE** parameter
- Verify the value that appears in the **VEL** parameter, when you press the  key
- The **maximum speed** value of the bridge will be **10 times** larger than the **VEL** showed.

Important:

- The **PULSE** value must always be greater than the value of **MEASURE** (the optimal value is "MEASURE x 10 = PULSE")
- Introduce the **MEASURE** value into the **unit of measure** that you choosen. Example: if you choose 1/10mm unit of measure and the **delta space** is 133.5mm, measure is 133.5mm, introduce the value 1335 into the **MEASURE** parameter
- The **Pulse** and **Measure** parameters inserted here, will be automatically transcribed into the **GP-18** and **GP-19** parameters



For exit from the **Bridge calibration** page press the  key

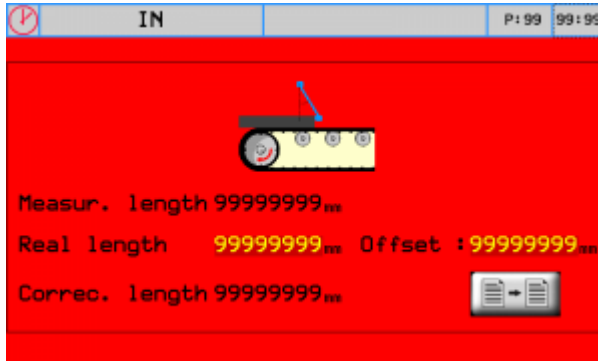
1. 5.4.3 Offset calibration of the pieces presence sensor

Offset calibration is used to calculate the difference between the **activation point** and the **deactivation point** of the limit-switch piece presence.



To access on the **offset calibration** page, press the key

The following page appears:



1. Measure the length of a piece;
2. Enter the length in the **Real length** parameter;
3. Start the conveyor (the instrument will read the length of the piece, using the sensor);
4. The instrument will show the length value of the piece on the **Measur. length** value;



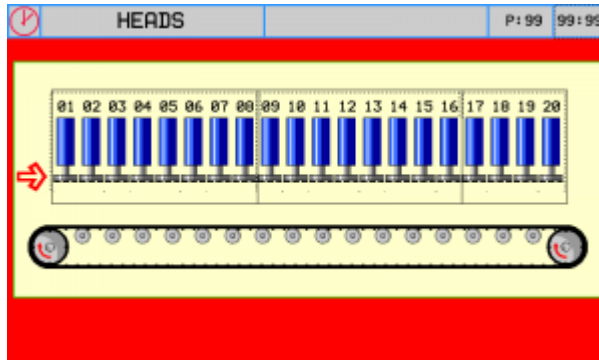
5. Press the key and the instrument will calculate the offset value of the limit-switch

1. 5.4.4 Set Heads parameters

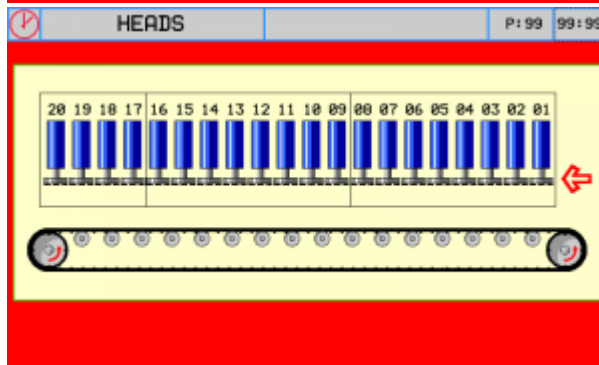


To access on the **Set Heads parameters** page, press the  key

The following page appears



or



Note:

With the *MP-16* parameter = **direction** of the pieces input, you choose (graphically) the direction of entry of the workpieces.

Head	Type	Interaxis	Diameter
1	9999	99999999 _{mm}	99999999 _{mm}
2	9999	99999999 _{mm}	99999999 _{mm}
3	9999	99999999 _{mm}	99999999 _{mm}
4	9999	99999999 _{mm}	99999999 _{mm}
5	9999	99999999 _{mm}	99999999 _{mm}
6	9999	99999999 _{mm}	99999999 _{mm}
7	9999	99999999 _{mm}	99999999 _{mm}
8	9999	99999999 _{mm}	99999999 _{mm}

Head	Type	Interaxis	Diameter
9	9999	99999999 _{mm}	99999999 _{mm}
10	9999	99999999 _{mm}	99999999 _{mm}
11	9999	99999999 _{mm}	99999999 _{mm}
12	9999	99999999 _{mm}	99999999 _{mm}
13	9999	99999999 _{mm}	99999999 _{mm}
14	9999	99999999 _{mm}	99999999 _{mm}
15	9999	99999999 _{mm}	99999999 _{mm}
16	9999	99999999 _{mm}	99999999 _{mm}

HEADS				P: 99	99: 99
Head	Type	Interaxis	Diameter		
17	9999	99999999 _{mm}	99999999 _{mm}		
18	9999	99999999 _{mm}	99999999 _{mm}		
19	9999	99999999 _{mm}	99999999 _{mm}		
20	9999	99999999 _{mm}	99999999 _{mm}		

Note:

Tap the touch to select the group of heads

Parameter name	Unit of measure	Default	Range	Description
Type	-	-	0 ÷ 5	How the head works. 0: disable 1: sander 2: milling 3: grinding 4: brushing 5: jet air/water
Wheelbase	mm	-	0 ÷ 99999.0	Space between the piece presence limit-switch and the center of the head .
Diameter	mm	-	0 ÷ 99999.0	Tool diameter.



For exit from the **Set Heads parameters** press the key

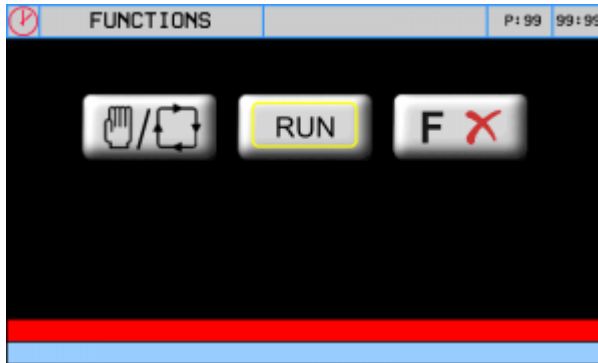
1. 5.4.5 Calibration of dynamic corrections ascent/descent heads



With this calibration, the heads will be **turned on/off** in the right place, even if the speed **of the conveyor belt is varied**.
Note: turn off the motor start by putting OFF the motor rotation start button.



To enter from the **MAIN MENU** press the key



Press the key to stop the motors



For return on the **MAIN MENU** page, press the key



To enter, from the **CALIBRATION** page, press the key

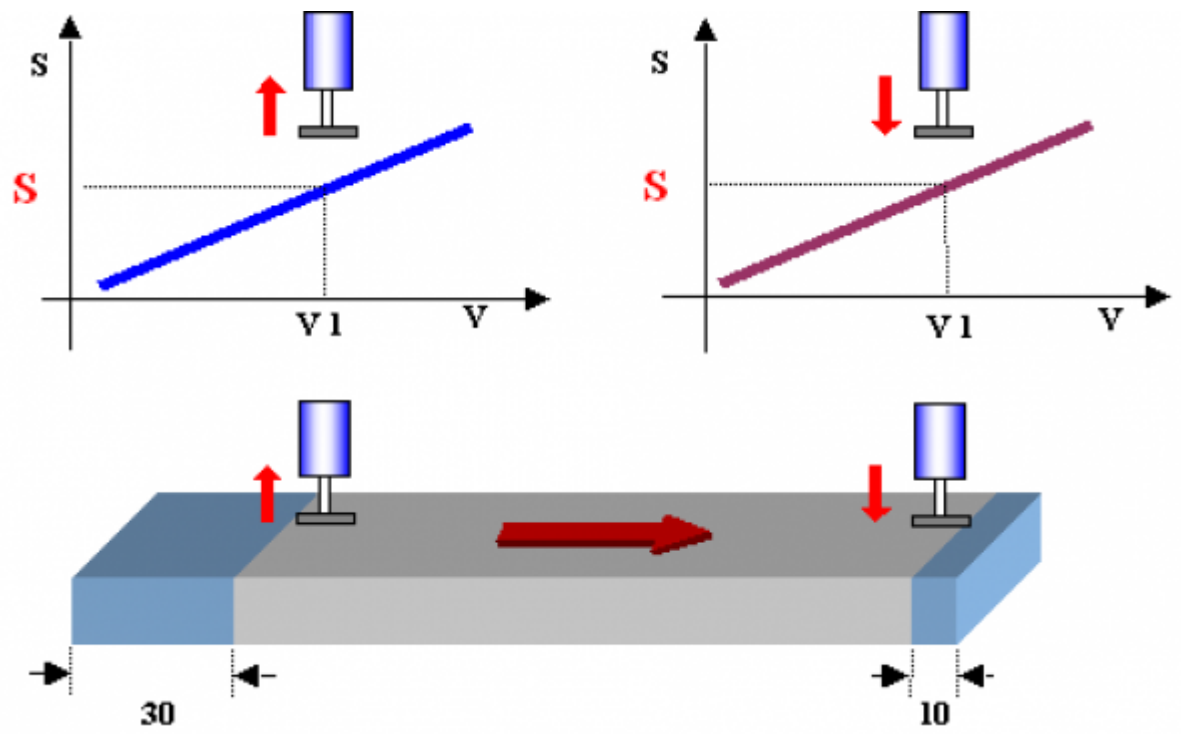
Head	Down lag	Rise adv
1	99999999 mm	99999999 mm
2	99999999 mm	99999999 mm
3	99999999 mm	99999999 mm
4	99999999 mm	99999999 mm
5	99999999 mm	99999999 mm
6	99999999 mm	99999999 mm
7	99999999 mm	99999999 mm
8	99999999 mm	99999999 mm

Copy the value to all other heads



Tap the touch to select the group of heads

Parameter	U.M.	Def.	Range	Description
CORR. VEL	m/''	3.0	0 ÷ 5.0	Reference speed of the dynamic calibration
Downlag	mm	-	-999.0 ÷ 999.0	(+) Delay space of the descent of the head from the begin piece
Risesdv	mm	-	-999.0 ÷ 999.0	(+) Advance space of the ascent of the head from the end piece

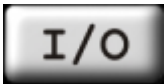


To smooth all the piece: $Downlag = 10$, $Risesdv = -30$

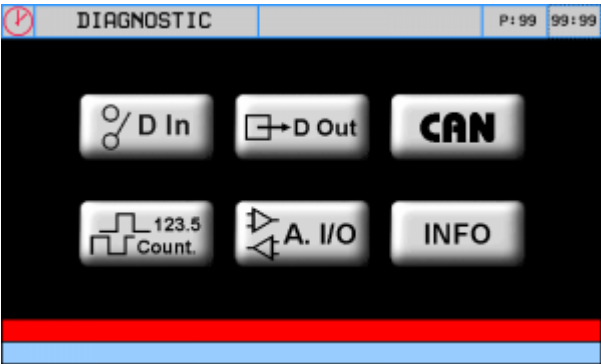


For exit from the **Calibration of dynamic corrections** press the key

1. 6. Diagnostic



To access on the diagnostic, from the **MENU** page, press the key



From this page you can access the various diagnostic sections:

	Digital inputs
	Digital outputs
	Counters
	Analog Inputs/Output
	Can informations
	System informations



To return on the **MENU**' page, press the key

1. 6.1 Digital inputs



To access the diagnostics page of the **Digital Inputs**, press the key

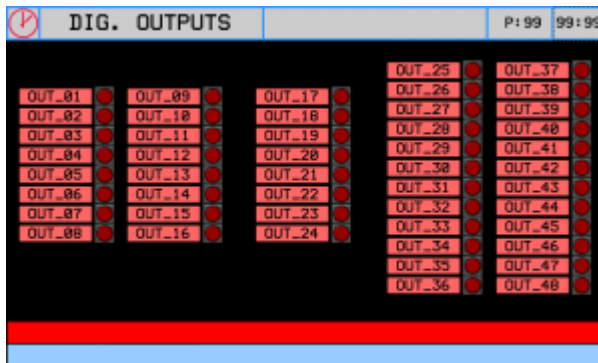


To return on the **DIAGNOSTIC** menu, press the key

6.2 Digital outputs



To access the diagnostics page of the **Digital Outputs** page, press the page



To return on the **DIAGNOSTIC** menu, press the key

6.3 Counters



To access the diagnostics page of the **Counters** page, press the key

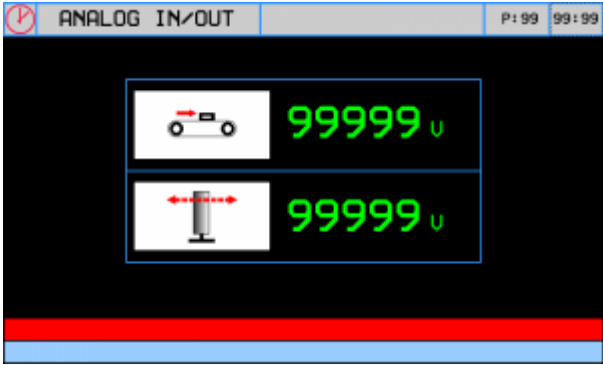


To return on the **DIAGNOSTIC** menu, press the key

6.4 Analog outputs



To access the diagnostics page of the **Analog outputs**, press the key



The analog output is showed in Volts.

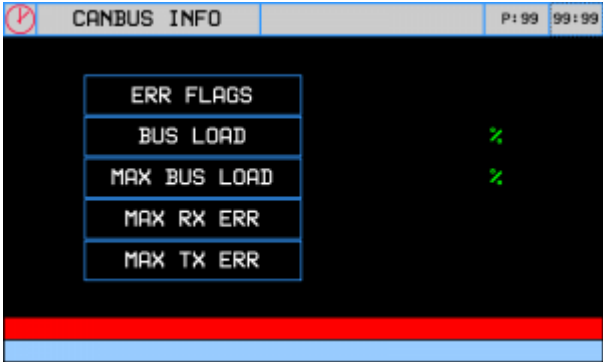


To return on the **DIAGNOSTIC** menu, press the key

6.5 CAN Informations



To access the diagnostics page of the **CanOpen Connection**, press the key

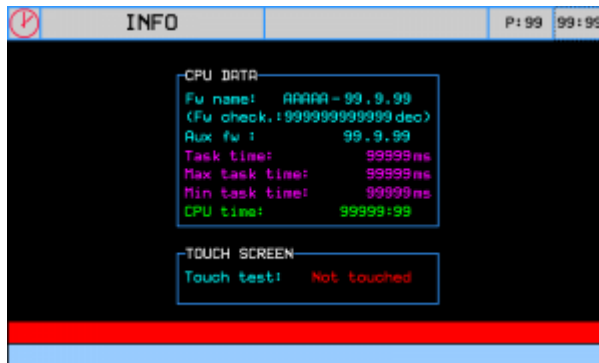


To return on the **DIAGNOSTIC** menu, press the key

1. 6.6 System informations



To access the diagnostics page of the **"System informations"**, press the **INFO** key



Fw name	firmware and checksum
Aux fw	firmware of the I/O module
Task time	CPU cycle time : Minimum, Middle, Maximum
CPU time	CPU time in the Run state (hh:mm)
Touch screen	Test touch



To return on the **DIAGNOSTIC** menu, press the **F7** key

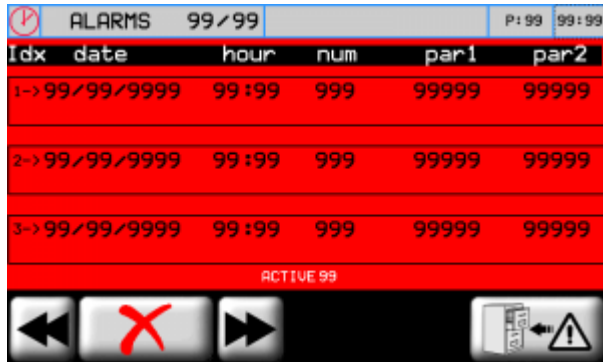
1. 7. Warning messages

Message	Description
Too many pieces in the car	There are more than 30 pieces in the car
Auxiliary Activation Wait...	Waiting auxiliary enablement (with <i>MP-08</i> enable) (I4 = ON)
Abrasive change quota positioning...	The bridge is controlled in the abrasive change position
Auxiliaries disabled	Auxiliaries disabled (I4 = OFF)
Attention!!! Motors off.	Attempting to Start tape with engines off

1. 8. Alarms



To access, from the **MAIN MENU**, press the key



Press the key for cancel the alarm

Message	Cause	Input
Emergency pressed	Check the emergency line	I01
Inverter Fault	Check the inverter	I12
Encoder belt Fault	Check the conveyor belt encoder (Enable only with <i>MP-03</i> > 2).	
Thermal protections	Check thermal protections	I06
Carter	Check perimeter protections	I07
No air	Check your pressure switch	I08



The **"Fault encoder belt"** message is automatically generated, if within 5 seconds there is no space greater than 2 units of measurement, the message is generated if the instrument detects a speed of less than 60mm per minute

8.1 History alarms



To access, from the **ALARMS** page, press the key



After **removing the causes** of the alarm, press (x 3 sec.) the key for cancel



Maximum 60 alarms.

1. 9. Various

9.1 Motor Start sequence

The motor start sequence can be executed in 3 modes (parameter **MP-05**)

1 = enable on J1-P20. **N.B.** Motor start outputs are in common with head descent outputs.

2 = enable on the RMC module.

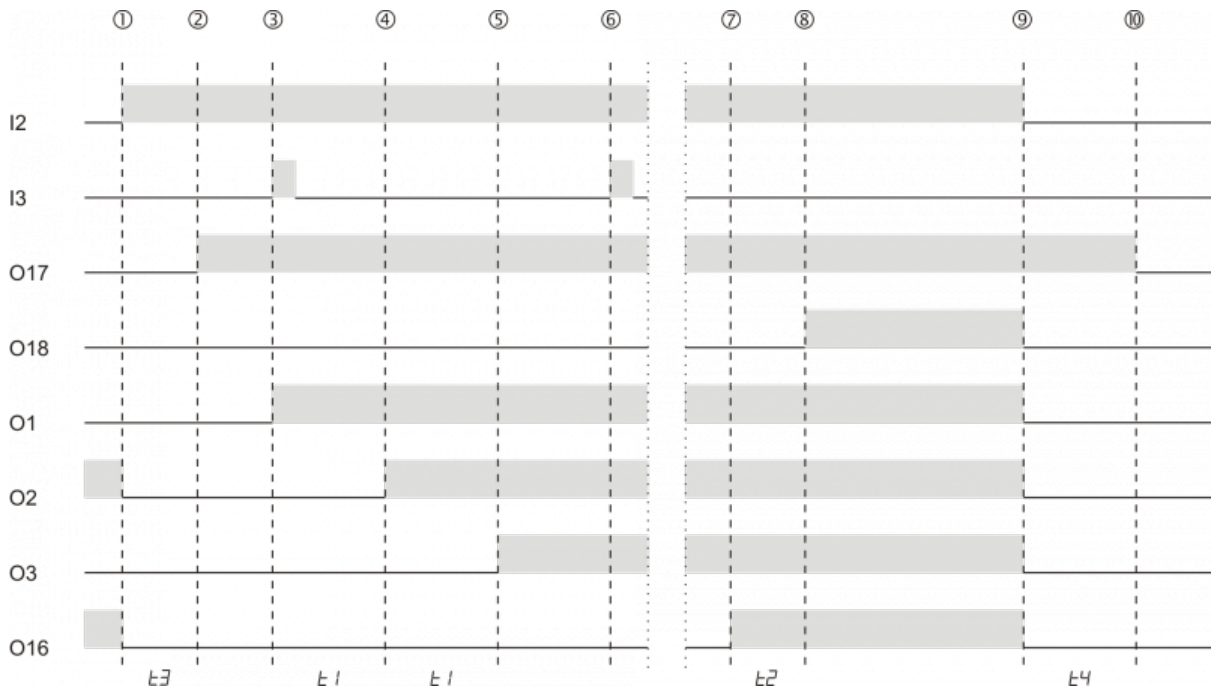
3 = enable on the RMC module. **N.B.** It is activated automatically at the entrance of the piece in the machine.

9.1.1 Start motors on J1-P20F (MP-05=1)

The motor start sequence uses the same outputs used for the head descent.

Input I2 determines whether the outputs are used for the descent control of the Heads or if they are used for starting motors.
Input I3 starts the motor sequence.

Below is the diagram of how the motor start sequence works with the **MP-05 = 1** parameter.



Legenda

- **I2** = Head activation (OFF) / Motors start (ON)
- **I3** = Motors start
- **O17** = Head activation (OFF) / Motors start (ON)
- **O1÷O16** = Heads command 1÷16
- **O18** = End of start-up

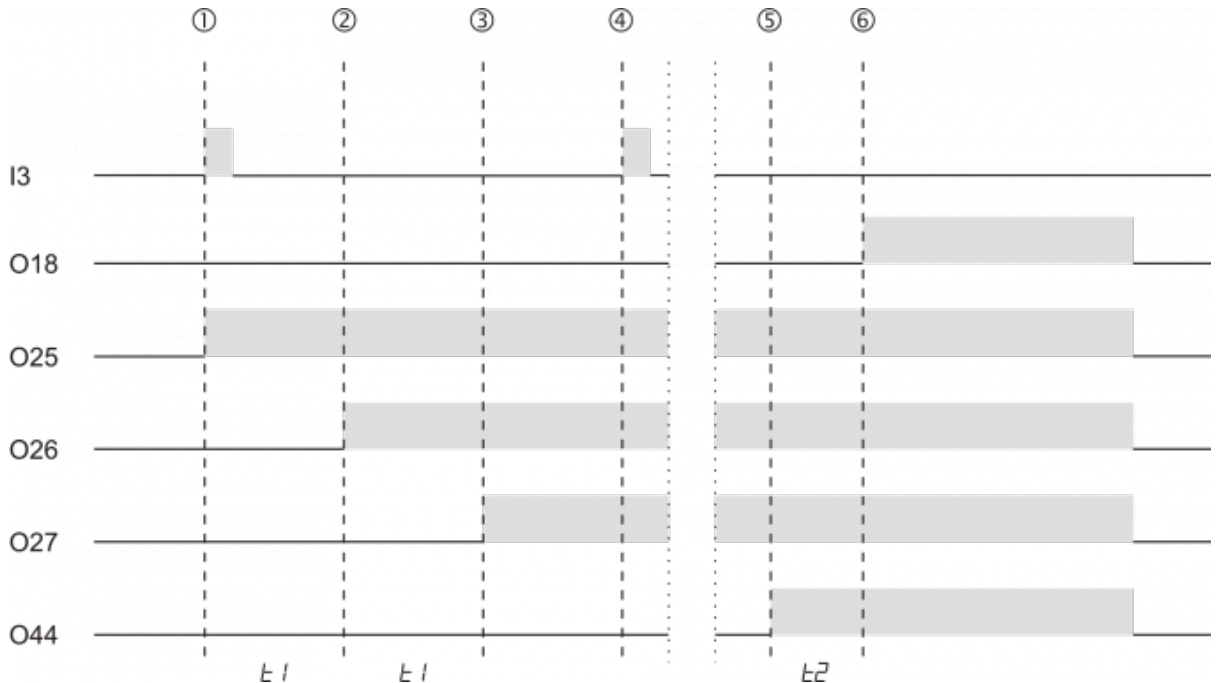
1. The input **I2** is activated and then the instrument changes the mode of operation from activating motor start heads. All head-related outputs (**O1÷O16**) are disabled.
2. After the $t3$ time (time passage operation heads descent / motors start) the instrument activate the **O17** output and enable the start motors operation.
3. When activating the **I3** input you have the beginning of the procedure of cascading motors and you activate the output relative to the first set-up-enabled head in ascending order.
4. After the $t1$ time (time interval motors start) you have the output activation for the next head enabled in set-up.
5. In the event that a start motor command is activated again (**I3**) is not processed. A new start command will only be processed in case the instrument first goes into operation activation heads (**O17** = OFF) and then come back in start motors operation mode (**O17** = ON).
6. The output of the last enabled head is activated and the start motor procedure is completed.
7. The **O18** output is activated after the $t2$ time (The time between the start-up of the last motor and the activation of the end-of-motor output **O18**).
8. Turn off the **I2** input and the instrument changes the way of operation from starting motors to head startin. All head-related outputs (**O1÷O16**) and the **O18** outputs are deactivated.
9. After the $t4$ time (start-activation step time) the instrument turns off the **O17** output and enables the heads activation operation mode.

9.1.2 Motors Start on RMC Module (MP-05=2)

The motor start sequence uses the outputs in the RMC module.

I2 input has no operation.
Input I3 starts the motor start sequence.

Below is the diagram of how the motor start sequence works with the **MP-05=2**.



Legenda

- **I3** = Motors start
- **O25÷O44** = Heads command 1÷20
- **O18** = End of start-up

1. When activating the **I3** input you have the beginning of the procedure of cascading motors 3. and you activate the output relative to the first set-up-enabled head in ascending order.
2. After the $t1$ time (time interval motors start) you have the output activation for the next head enabled in set-up.
3. In the event that a start motor command is activated again (**I3**) 5. is not processed.
4. The output of the last enabled head is activated and the start motor procedure is completed.
5. The **O18** output is activated after the $t2$ time (The time between the start-up of the last motor and the activation of the end-of-motor output **O18**).

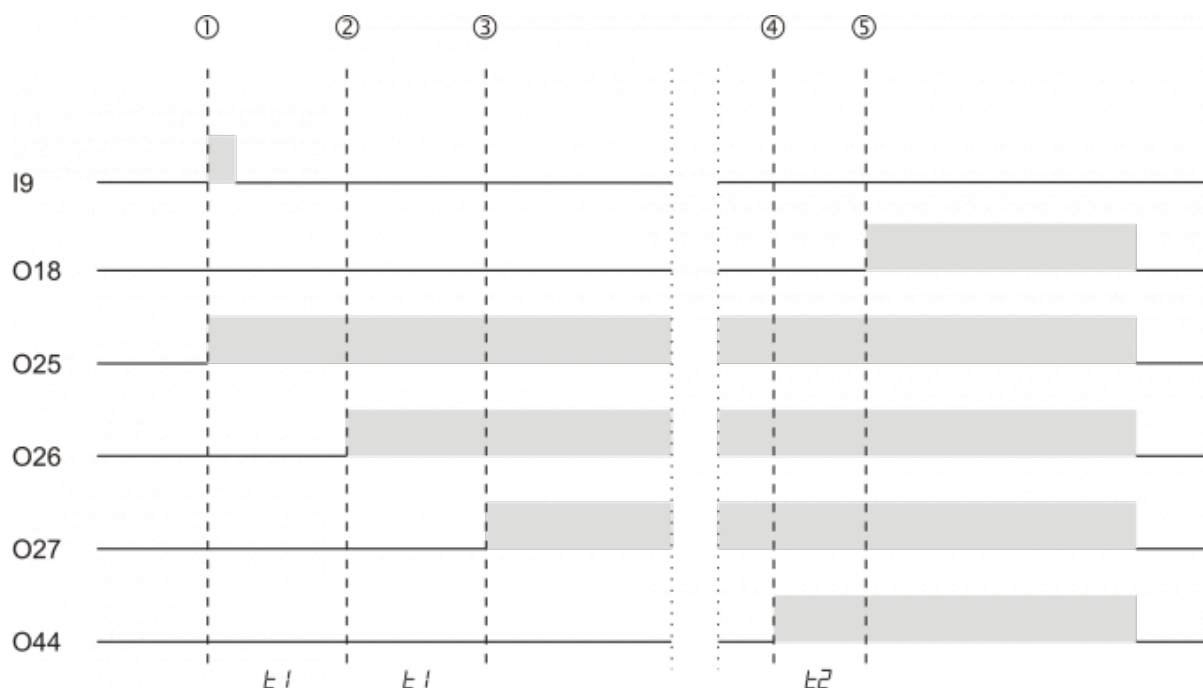
9.1.3 Avviamento Motori su Modulo RMC (MP-05=3)

La sequenza di avviamento motori utilizza le uscite utilizzate nel modulo RMC.

L'ingresso I2 non ha nessun funzionamento.
L'ingresso I3 non ha nessun funzionamento.

La sequenza di "avviamento motori" viene avviata automaticamente non appena "entra" il primo pezzo in macchina. N.B. Quando l'ultimo pezzo lavorato "esce" dalla macchina, le uscite avviamento motori si disattivano.

Qui di seguito il diagramma di funzionamento della sequenza avvio motori con il parametro **MP-05=3**.

**Legenda**

- **I9** = Acquisizione pezzo
 - **O25+O44** = Comando teste 1÷20
 - **O18** = Fine avviamento
1. All'attivazione dell'ingresso **I9** si ha l'inizio della procedura di partenza in cascata dei motori e si attiva l'uscita relativa alla prima testa abilitata in set-up in ordine crescente.
 2. Trascorso il tempo $t1$ (tempo intervallo start motori) si ha l'attivazione dell'uscita relativa alla successiva testa abilitata in set-up.
 3. Trascorso il tempo $t1$ (tempo intervallo start motori) si ha l'attivazione dell'uscita relativa alla successiva testa abilitata in set-up.
 4. Si attiva l'uscita dell'ultima testa abilitata e ha termine la procedura di start motori.
 5. Si attiva l'uscita **O18** dopo il tempo $t2$ (Tempo che intercorre tra l'avviamento dell'ultimo motore e l'attivazione dell'uscita di fine avviamento motori **O18**).

1. 10. Assistance

For supplying you fast service, at the lowest cost, we need your support.

	
Follow all instructions provided in the MIMAT manual	If the problem remains, fill out the "Request Form for assistance" on the page Contacts at www.qem.it site. Our technicians will get elements essential for the understanding of your problem.

Repair

To provide you with an efficient service, please read and adhere to the instructions given [here](#)

Shipping

It is recommended to pack the instrument with materials that are able to cushion any falls.

		
Use the original package: it must protect the instrument during transport.	Attach: 1. A description of the anomaly; 2. A part of the electric scheme where the equipment is inserted 3. The planning of the equipment (set up, quotas of job, parameters...). 4. Request a quote for repair; if not required, the cost will be calculated in the final balance.	A full description of the problem, will help identify and resolve your problems fast. A careful packaging will avoid further inconveniences.

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